

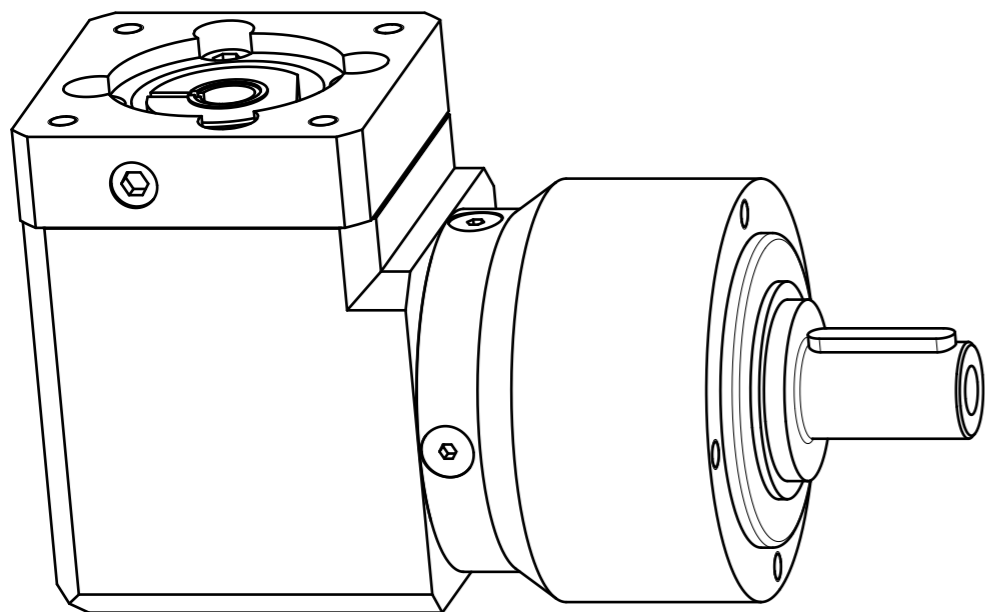
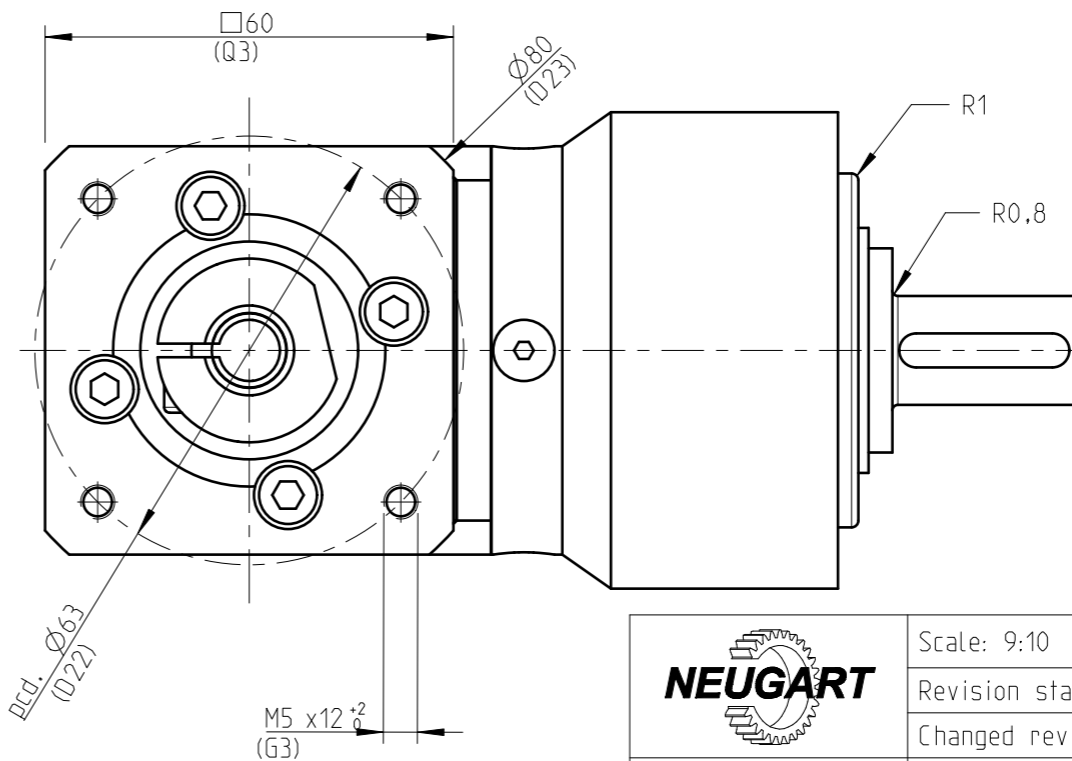
**Materials / Surfaces:**


Input flange: Aluminum / untreated  
 Angle housing: Aluminum / untreated  
 Housing: Steel / heat-treated and post-oxidized (black)  
 Output flange: Steel / heat-treated and post-oxidized (black)

**Hints:**

Please pay attention to the operating and mounting instructions.  
 Subject to modifications.

Variables on the drawing are dependent upon the motor.  
 The given dimensions are exemplary.



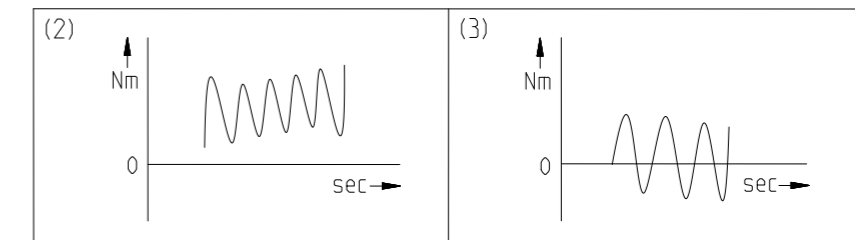
	Scale: 9:10	DIN A3	ISO
	Revision status: G from: 09/2022		
Changed revision status: F from: 02/2022			
General tolerance DIN ISO 2768-cL	W PLPE070-aii-SSSA3AC-Y(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Bevel gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	1-stage
Output shaft bearing	-	-	Deep groove ball bearing
Service life (L10h)	t <sub>L</sub>	h	20.000
Max. operating temperature	T <sub>min</sub> / T <sub>max</sub>	°C	-25 / +90
Protection class	-	-	IP 54
Right angle gearbox lubrication (lubricated for life)	-	-	Standard lubrication (KLüberplex BEM 34-132)
Planetary gearbox lubrication (lubricated for life)	-	-	Standard lubrication (KLübersynth GE 14-112)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M <sub>b</sub>	Nm	5
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	mm	0,03 / 0,06 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	L <sub>20 min</sub>	mm	14,5
Reference operating mode	-	-	S1
Reference operating factor	K <sub>A</sub>	-	1
Reference speed	n <sub>2</sub>	rpm	100
Reference ambient temperature	T <sub>Amb</sub>	°C	20
Radial force for output bearing based on shaft center after L10h=20,000h with Fa=0N	F <sub>r 20.000h</sub>	N	1050
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	F <sub>a 20.000h</sub>	N	1350
Radial force for output bearing based on shaft center after L10h=30,000h with Fa=0N	F <sub>r 30.000h</sub>	N	900
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	F <sub>a 30.000h</sub>	N	1000
Maximum radial force based on shaft center and T2=0Nm	F <sub>r Max</sub>	N	1650
Maximum axial force based on gearbox axis and T2=0Nm	F <sub>a Max</sub>	N	2100

Ratio-dependent gearbox data	Character	Unit						
Ratio	a <sub>ii</sub>	-	3	4	5	7	8	10
Nominal output torque No alternating torque (2)	T <sub>2N</sub>	Nm	14	19	24	25	18	15
Nominal output torque Alternating torque permitted for 10,000,000 load changes (3)	T <sub>2N 10Mio</sub>	Nm	14	19	24	25	18	15
Nominal output torque Alternating torque permitted for 100,000,000 load changes (3)	T <sub>2N 100Mio</sub>	Nm	14	19	24	25	18	15
Max. output torque for 30,000 output shaft rotations (2)	T <sub>2max</sub>	Nm	22	30	38	40	29	24
Emergency stop torque permitted 1000 times	T <sub>2Stop</sub>	Nm	66	86	80	80	80	70
Average idle torque for n1=3,000 rpm and 20 °C gearbox temperature	T <sub>0</sub>	Nm	0,2	0,15	0,15	0,15	0,15	0,15
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n <sub>1N 50%</sub>	rpm	4200	4500	4500	4500	4500	4500
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n <sub>1N 100%</sub>	rpm	3300	3500	3600	4300	4500	4500
Max. mechanical input speed Operating temperature may not be exceeded!	n <sub>1 Limit</sub>	rpm	13000	13000	13000	13000	13000	13000
Torsional backlash based on output shaft	j <sub>t</sub>	arcmin	< 16	< 16	< 16	< 16	< 16	< 16
Torsional stiffness based on output shaft	c <sub>g</sub>	Nm/arcmin	2,2	3,1	3,7	3,8	3,8	3,5
Efficiency at T2N, gearbox temperature 70 °C and n1=1,000rpm	η	%	94	94	95	94	93	91
Running noise at n1=3,000 rpm without load at a distance of 1m	Q <sub>g</sub>	dB(A)	70	70	70	70	70	70
Gearbox weight	m <sub>G</sub>	kg	2,1	2,1	2,1	2,1	2,2	2,2
Mass moment of inertia based on clamping system diameter input	J	kgcm <sup>2</sup>	0,324	0,225	0,219	0,214	0,214	0,213

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- \* with symmetrically distributed motor weight
- \* with horizontal and stationary mounting



Subject to modifications.



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/(L20)/(D21)/(D22)/B5/(G3)

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