

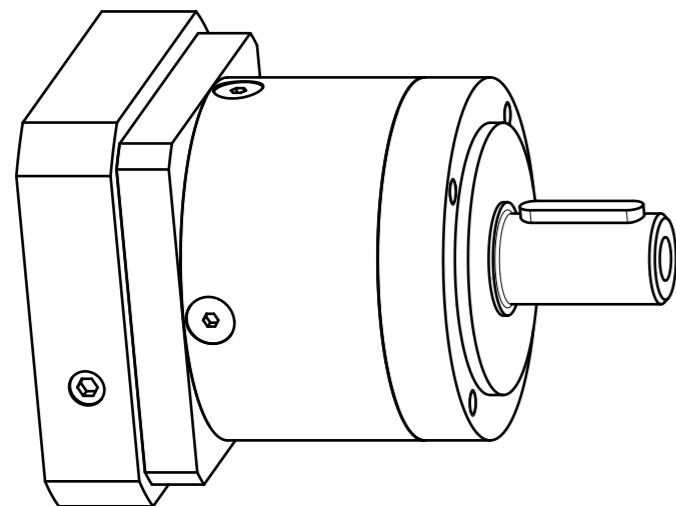
Materials / Surfaces:


Input flange: Aluminum / untreated
 Housing: Steel / heat-treated and post-oxidized (black)
 Output flange: Aluminum / untreated

Hints:

Please pay attention to the operating and mounting instructions.
 Subject to modifications.

Variables on the drawing are dependent upon the motor.
 The given dimensions are exemplary.



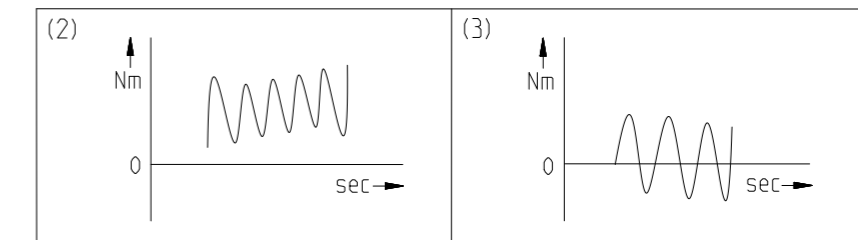
	Scale: 7:10	DIN A3	ISO
	Revision status: L from: 07/2022		
	Changed revision status: K from: 11/2021		
General tolerance DIN ISO 2768-cl	PLE080-aii-SSSA3AE-Y(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	1-stage
Output shaft bearing	-	-	Deep groove ball bearing
Service life (L10h)	t_L	h	30.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 54
Lubrication (lifetime lubrication)	-	-	Standard lubrication (Klübersynth GE 14-112)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	16
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	mm	0,04 / 0,08 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20 min}$	mm	19
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20,000h with Fa=0N	$F_r 20.000h$	N	750
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	$F_a 20.000h$	N	1000
Radial force for output bearing based on shaft center after L10h=30,000h with Fa=0N	$F_r 30.000h$	N	650
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	$F_a 30.000h$	N	900
Maximum radial force based on shaft center and T2=0Nm	$F_r Max$	N	1250
Maximum axial force based on gearbox axis and T2=0Nm	$F_a Max$	N	1600

Ratio-dependent gearbox data	Character	Unit						
Ratio	aii	-	3	4	5	7	8	10
Nominal output torque No alternating torque (2)	T_{2N}	Nm	85	115	110	65	50	38
Nominal output torque Alternating torque permitted for 10,000,000 load changes (3)	$T_{2N 10Mio}$	Nm	68	68	68	65	50	38
Nominal output torque Alternating torque permitted for 100,000,000 load changes (3)	$T_{2N 100Mio}$	Nm	54	54	54	54	50	38
Max. output torque for 30,000 output shaft rotations (2)	T_{2max}	Nm	136	184	176	104	80	61
Emergency stop torque permitted 1000 times	T_{2Stop}	Nm	180	240	220	178	190	200
Average idle torque for $n_1=3,000$ rpm and 20 °C gearbox temperature	T_0	Nm	0,35	0,35	0,25	0,2	0,2	0,2
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 50\%}$	rpm	4000	3900	4000	4000	4000	4000
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 100\%}$	rpm	2700	2500	3000	4000	4000	4000
Max. mechanical input speed Operating temperature may not be exceeded!	$n_1 Limit$	rpm	7000	7000	7000	7000	7000	7000
Torsional backlash based on output shaft	j_t	arcmin	< 7	< 7	< 7	< 7	< 7	< 7
Torsional stiffness based on output shaft	c_g	Nm/arcmin	7,2	9,2	9,4	8,1	8	7,5
Efficiency at T2N, gearbox temperature 70 °C and $n_1=1,000$ rpm	η	%	98	98	98	97	97	96
Running noise at $n_1=3,000$ rpm without load at a distance of 1m	Q_g	dB(A)	60	60	60	60	60	60
Gearbox weight	m_G	kg	2,1	2,1	2,2	2,1	2,1	2,2
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	0,654	0,455	0,423	0,379	0,37	0,359

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting



Subject to modifications.



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/(L20)/(D21)/(D22)/B5/(G3)

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