

Flange output shaft (similar ISO 9409-1)

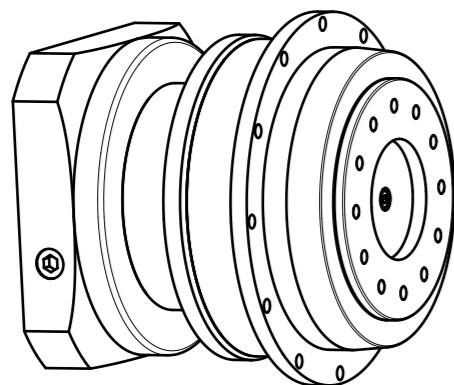
Materials / Surfaces:


Input flange: Aluminum / untreated
Housing: Steel / heat-treated and post-oxidized (black)
Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
Subject to modifications.

Variables on the drawing are dependent upon the motor.
The given dimensions are exemplary.



	Scale: 3:10	DIN A3	ISO
	Revision status: H from: 04/2022		
	Changed revision status: G from: 02/2020		
General tolerance DIN ISO 2768-cL	PSFN200-bii-SSSD3AH-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Helical teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	2-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (Lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/220)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	180
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	mm	0,025 / 0,05 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20 min}$	mm	36
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft end after L10h=20,000h with Fa=0N	$F_r 20.000h$	N	23000
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	$F_a 20.000h$	N	16000
Radial force for output bearing based on shaft end after L10h=30,000h with Fa=0N	$F_r 30.000h$	N	21000
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	$F_a 30.000h$	N	14000
Maximum radial force based on shaft end and T2=0Nm	$F_r Max$	N	23000
Maximum axial force based on gearbox axis and T2=0Nm	$F_a Max$	N	16000

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting

Ratio-dependent gearbox data	Character	Unit								
Ratio	bii	-	16	20	25	35	40	50	70	100
Nominal output torque	T_{2N}	Nm	950	950	950	950	950	950	900	750
Max. output torque for 30,000 output shaft rotations	T_{2max}	Nm	1520	1520	1520	1520	1520	1520	1440	1200
Emergency stop torque permitted 1000 times	T_{2stop}	Nm	3200	3200	3200	3200	3200	3200	3200	1700
Average idle torque for $n_1=3,000$ rpm and 20 °C gearbox temperature	T_0	Nm	8	5,5	4,9	3,1	2,3	2,1	1,9	1,8
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 50\%}$	rpm	1550	1900	2050	2650	3000	3000	3000	3000
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 100\%}$	rpm	1400	1700	1900	2450	2800	3000	3000	3000
Max. mechanical input speed Operating temperature may not be exceeded!	$n_{1 Limit}$	rpm	6500	6500	6500	6500	6500	6500	6500	6500
Torsional backlash based on output shaft	j_t	arcmin	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5
Torsional stiffness based on output shaft	c_g	Nm/arcmin	664	669	576	561	597	540	461	365
Efficiency at T2N, gearbox temperature 70 °C and $n_1=1,000$ rpm	η	%	96	96	96	95	95	95	93	91
Running noise at $n_1=3,000$ rpm without load at a distance of 1m	Q_g	dB(A)	68	68	68	68	68	68	68	68
Gearbox weight	m_G	kg	36,9	37	37,5	37,6	36,9	37,3	37,6	37,8
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	13,977	12,297	11,937	10,732	10,204	10,114	10,038	10,001



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