

Flange output shaft (similar ISO 9409-1)

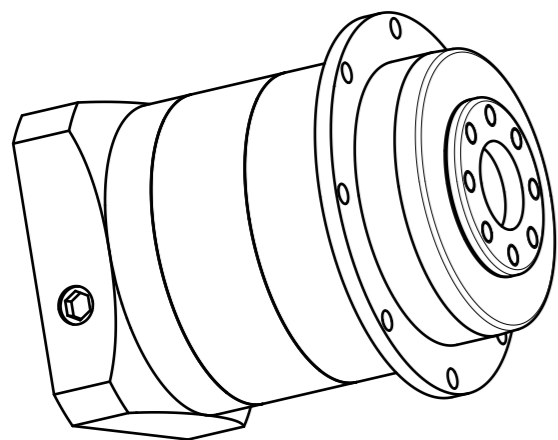
Materials / Surfaces:


Input flange: Aluminum / untreated
 Housing: Steel / heat-treated and post-oxidized (black)
 Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
 Subject to modifications.

Variables on the drawing are dependent upon the motor.
 The given dimensions are exemplary



	Scale: 9:10	DIN A3	ISO
	Revision status: Q from: 05/2022		
	Changed revision status: P from: 01/2021		
General tolerance DIN ISO 2768-cL	PLFN064-bii-SSSD3AD-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	2-stage
Output shaft bearing	-	-	Inclined roller bearings
Service life (L10h)	t _L	h	20.000
Max. operating temperature	T _{min} / T _{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (Lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/150)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M _b	Nm	18
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	mm	0,015 / 0,03 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	L _{20 min}	mm	15
Reference operating mode	-	-	S1
Reference operating factor	K _A	-	1
Reference speed	n ₂	rpm	100
Reference ambient temperature	T _{Amb}	°C	20
Radial force for output bearing based on shaft end after L10h=20,000h with Fa=0N	F _{r 20.000h}	N	2150
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	F _{a 20.000h}	N	4300
Radial force for output bearing based on shaft end after L10h=30,000h with Fa=0N	F _{r 30.000h}	N	1900
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	F _{a 30.000h}	N	3800
Maximum radial force based on shaft end and T2=0Nm	F _{r Max}	N	2150
Maximum axial force based on gearbox axis and T2=0Nm	F _{a Max}	N	4300

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting

Ratio-dependent gearbox data	Character	Unit								
Ratio	bii	-	16	20	25	32	40	50	64	100
Nominal output torque	T _{2N}	Nm	77	77	65	77	65	65	40	27
Max. output torque for 30.000 output shaft rotations	T _{2max}	Nm	123	123	104	123	104	104	64	43
Emergency stop torque permitted 1000 times	T _{2stop}	Nm	150	150	150	150	150	150	80	80
Average idle torque for n1=3,000 rpm and 20 °C gearbox temperature	T ₀	Nm	0,35	0,3	0,25	0,25	0,2	0,2	0,2	0,2
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n _{1N 50%}	rpm	3700	4200	4500	4500	4500	4500	4500	4500
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n _{1N 100%}	rpm	3050	3500	4000	4400	4500	4500	4500	4500
Max. mechanical input speed Operating temperature may not be exceeded!	n _{1 Limit}	rpm	14000	14000	14000	14000	14000	14000	14000	14000
Torsional backlash based on output shaft	j _t	arcmin	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5
Torsional stiffness based on output shaft	c _g	Nm/arcmin	13,6	13,7	14,7	13,4	14,5	14,3	10	7,6
Efficiency at T2N, gearbox temperature 70 °C and n1=1,000rpm	η	%	94	94	92	92	90	88	81	68
Running noise at n1=3,000 rpm without load at a distance of 1m	Q _g	dB(A)	60	60	60	60	60	60	60	60
Gearbox weight	m _G	kg	1,9	1,9	1,9	1,9	1,9	1,9	1,9	1,95
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	0,243	0,228	0,226	0,213	0,21	0,21	0,212	0,209



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