

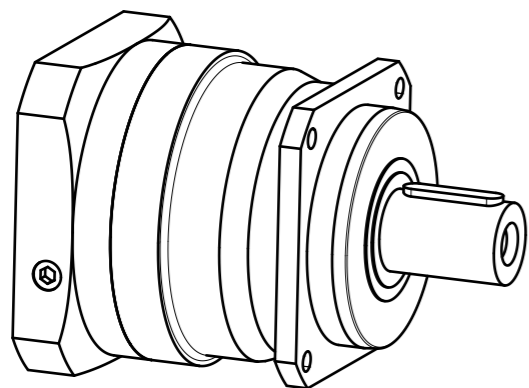
Materials / Surfaces:


Input flange: Aluminum / untreated
 Housing: Steel / heat-treated and post-oxidized (black)
 Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
 Subject to modifications.

Variables on the drawing are dependent upon the motor.
 The given dimensions are exemplary.

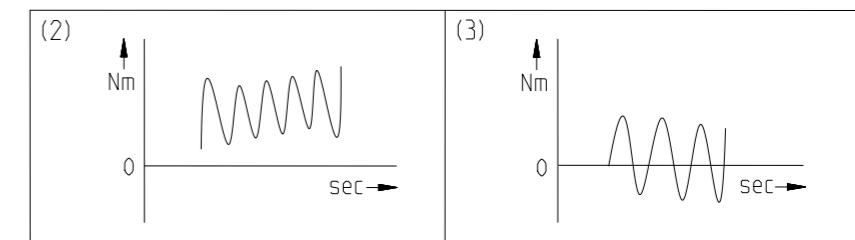


	Scale: 3:10	DIN A3	ISO
	Revision status: E from: 04/2022		
	Changed revision status: D from: 03/2020		
General tolerance DIN ISO 2768-cL	PSN190-aii-SSSA3AK-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Helical teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	1-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (Lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/220)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	300
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	-	0,025 / 0,05 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20 min}$	mm	37
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20,000h with Fa=0N	$F_r 20.000h$	N	20000
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	$F_a 20.000h$	N	19000
Radial force for output bearing based on shaft center after L10h=30,000h with Fa=0N	$F_r 30.000h$	N	17500
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	$F_a 30.000h$	N	18500
Maximum radial force based on shaft center and T2=0Nm	$F_r Max$	N	20000
Maximum axial force based on gearbox axis and T2=0Nm	$F_a Max$	N	19000

$$(1) \text{ Max. motor weight* in kg} = \frac{0.2 \times M_b}{\text{motor length in m}}$$

* with symmetrically distributed motor weight
* with horizontal and stationary mounting



Ratio-dependent gearbox data	Character	Unit					
Ratio	aii	-	3	4	5	7	10
Nominal output torque No alternating torque (2)	T_{2N}	Nm	845	950	950	900	750
Nominal output torque Alternating torque permitted for 10,000,000 load changes (3)	$T_{2N 10Mio}$	Nm	693	693	693	693	693
Nominal output torque Alternating torque permitted for 100,000,000 load changes (3)	$T_{2N 100Mio}$	Nm	550	550	550	550	550
Max. output torque for 30,000 output shaft rotations (2)	T_{2max}	Nm	1352	1520	1520	1440	1200
Emergency stop torque permitted 1000 times	T_{2Stop}	Nm	2400	3200	3200	3200	1700
Average idle torque for $n_1=3,000$ rpm and 20 °C gearbox temperature	T_0	Nm	20,3	16	10,6	6,5	4,3
Average thermal input speed at 50% T_{2N} , S1, and T_{Amb} Operating temperature may not be exceeded!	$n_{1N 50\%}$	rpm	750	900	1100	1450	1900
Average thermal input speed at 100% T_{2N} , S1, and T_{Amb} Operating temperature may not be exceeded!	$n_{1N 100\%}$	rpm	700	800	950	1300	1700
Max. mechanical input speed Operating temperature may not be exceeded!	$n_1 Limit$	rpm	6000	6000	6000	6000	6000
Torsional backlash based on output shaft	j_t	arcmin	< 3	< 3	< 3	< 3	< 3
Torsional stiffness based on output shaft	c_g	Nm/arcmin	204	215	221	204	181
Efficiency at T_{2N} , gearbox temperature 70 °C and $n_1=1,000$ rpm	η	%	98	98	98	98	97
Running noise at $n_1=3,000$ rpm without load at a distance of 1m	Q_g	dB(A)	73	68	68	68	68
Gearbox weight	m_G	kg	36,7	34,9	35,3	35,6	35,8
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	53,182	35,779	29,383	24,539	21,695

Subject to modifications.



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