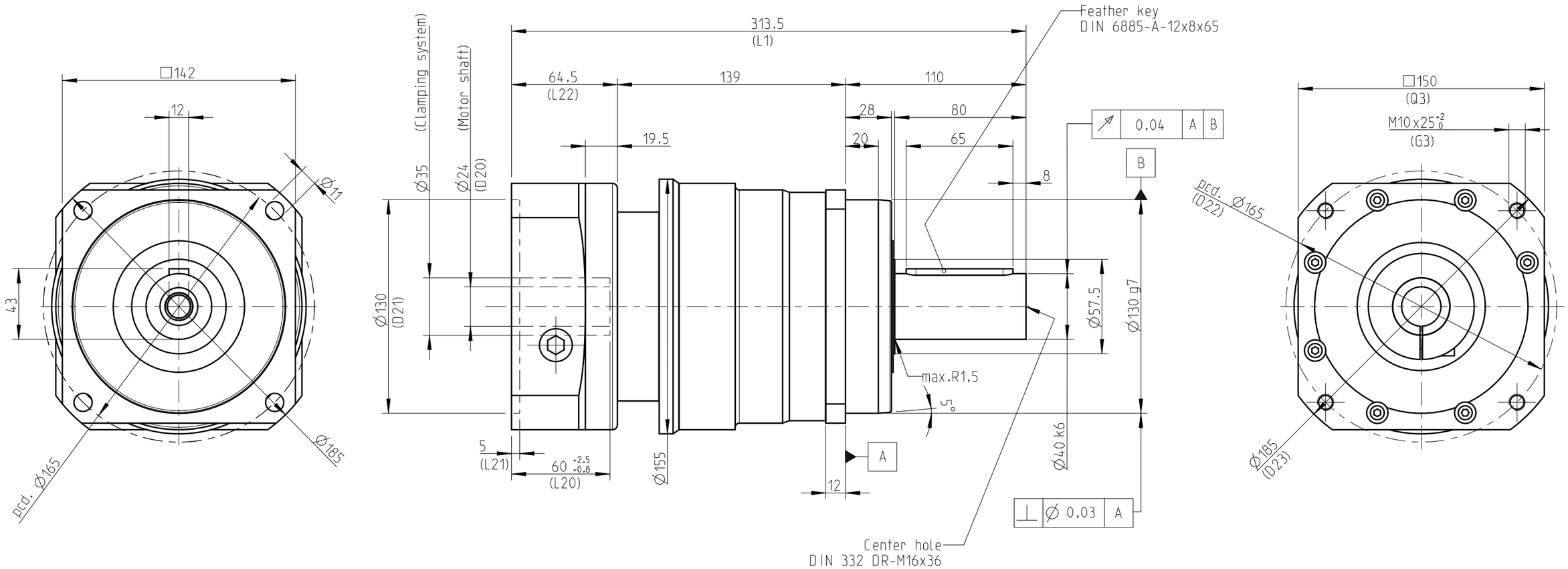


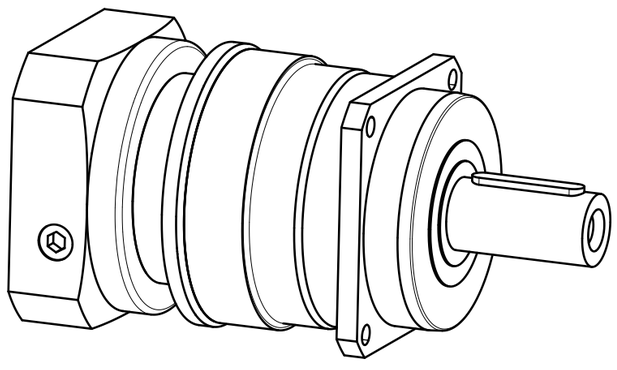
Materials / Surfaces:

Input flange: Aluminum / untreated
Housing: Steel / heat-treated and post-oxidized (black)
Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
Subject to modifications.

Variables on the drawing are dependent upon the motor.
The given dimensions are exemplary.

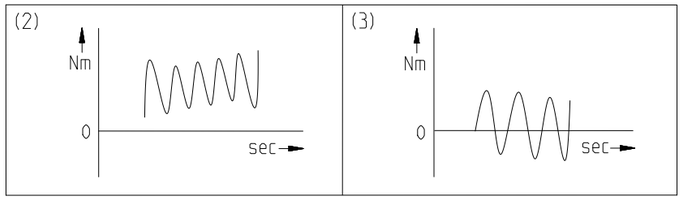


NEUGART	Scale: 2:5	DIN A3	ISO
	Revision status: E from: 04/2022		
	Changed revision status: D from: 03/2020		
General tolerance DIN ISO 2768-cL	PSN142-bii-SSSA3AG-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Helical teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	2-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/220)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	80
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	-	0,02 / 0,05 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20\ min}$	mm	39
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20.000h with Fa=0N	$F_{r\ 20.000h}$	N	13000
Axial force for output bearing based on gearbox axis after L10h=20.000h with Fr=0N	$F_{a\ 20.000h}$	N	15000
Radial force for output bearing based on shaft center after L10h=30.000h with Fa=0N	$F_{r\ 30.000h}$	N	11500
Axial force for output bearing based on gearbox axis after L10h=30.000h with Fr=0N	$F_{a\ 30.000h}$	N	13500
Maximum radial force based on shaft center and T2=0Nm	$F_{r\ Max}$	N	13000
Maximum axial force based on gearbox axis and T2=0Nm	$F_{a\ Max}$	N	15000

(1) Max. motor weight* in kg = $\dfrac{0{,}2 \times M_b}{\text{motor length in m}}$

* with symmetrically distributed motor weight
* with horizontal and stationary mounting



Ratio-dependent gearbox data	Character	Unit										
Ratio	bii	-	12	15	16	20	25	35	40	50	70	100
Nominal output torque No alternating torque (2)	T_{2N}	Nm	380	380	450	450	405	405	470	405	355	305
Nominal output torque Alternating torque permitted for 10.000.000 load changes (3)	$T_{2N\ 10Mio}$	Nm	380	380	401	401	401	401	401	401	355	305
Nominal output torque Alternating torque permitted for 100.000.000 load changes (3)	$T_{2N\ 100Mio}$	Nm	319	319	319	319	319	319	319	319	319	305
Max. output torque for 30.000 output shaft rotations (2)	T_{2max}	Nm	608	608	720	720	648	648	752	648	568	488
Emergency stop torque permitted 1000 times	T_{2Stop}	Nm	1250	1250	1650	1650	1650	1650	1650	1650	1300	600
Average idle torque for n1=3.000 rpm and 20 °C gearbox temperature	T_0	Nm	3,6	2,5	3,3	2,25	2,1	1,35	1	0,95	0,9	0,9
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N\ 50\%}$	rpm	2350	2900	2550	3150	3400	3500	3500	3500	3500	3500
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N\ 100\%}$	rpm	2150	2650	2350	2850	3150	3500	3500	3500	3500	3500
Max. mechanical input speed Operating temperature may not be exceeded!	$n_{1\ Limit}$	rpm	8500	8500	8500	8500	8500	8500	8500	8500	8500	8500
Torsional backlash based on output shaft	j_t	arcmin	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5
Torsional stiffness based on output shaft	c_g	Nm/arcmin	68	68	74	74	75	75	73	74	68	61
Efficiency at T2N, gearbox temperature 70 °C and n1=1.000rpm	η	%	96	96	96	96	96	95	96	95	93	90
Running noise at n1=3.000 rpm without load at a distance of 1m	Q_g	dB(A)	66	66	66	66	66	66	66	66	66	66
Gearbox weight	m_G	kg	19,1	19,3	19,3	19,4	19,5	19,4	19,4	19,4	19,6	19,7
Mass moment of inertia based on clamping system diameter input	J	kgcm²	4,817	4,31	4,589	4,164	4,103	3,865	3,74	3,725	3,714	3,696

Subject to modifications.

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PSN142-bii-SSSA3AG-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)

Revision status: E from: 04/2022