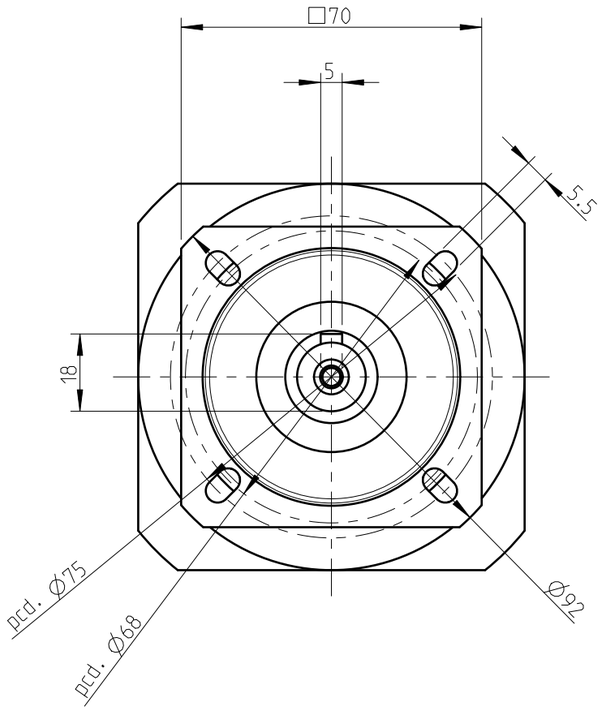
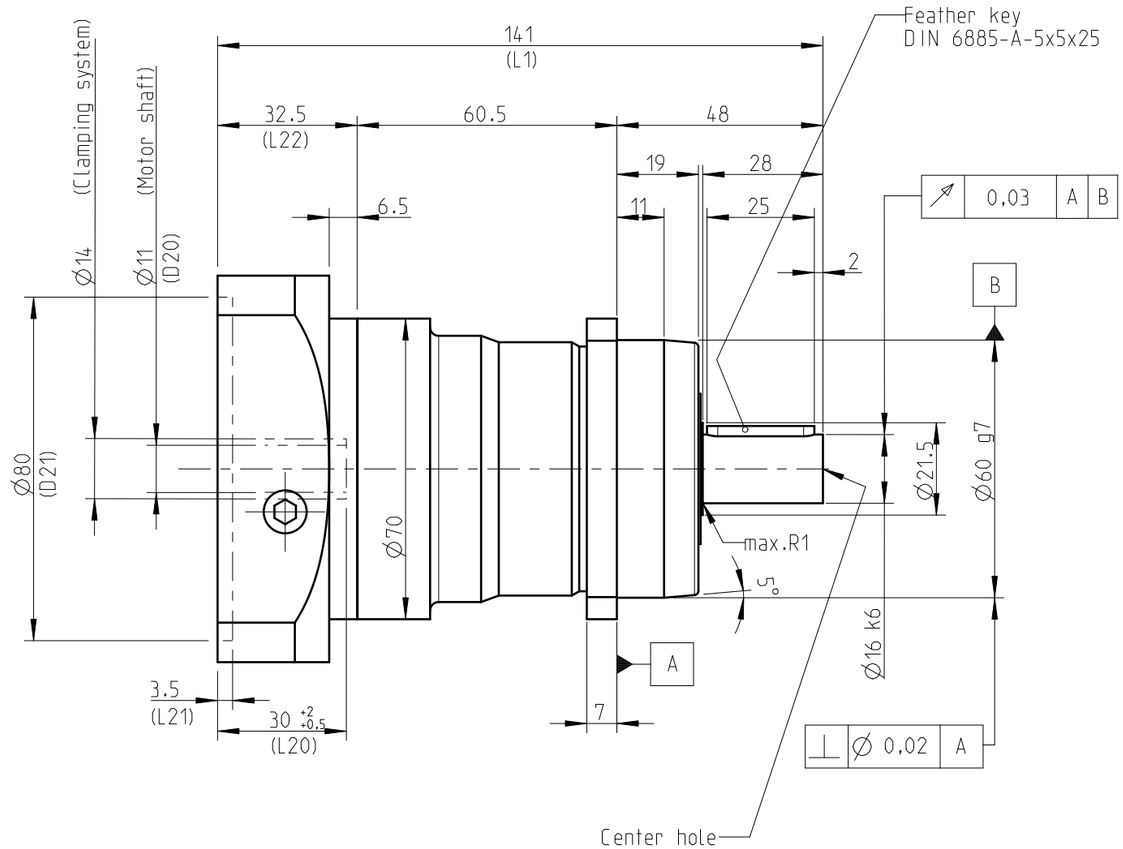
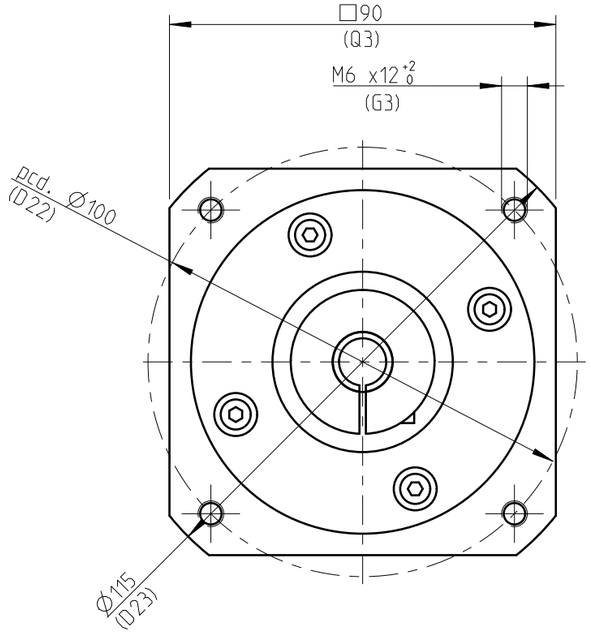






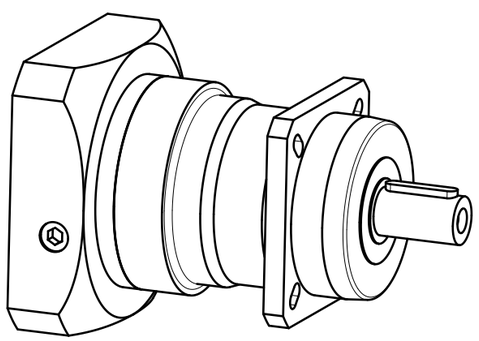
Materials / Surfaces:

Input flange: Aluminum / untreated
Housing: Steel / heat-treated and post-oxidized (black)
Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
Subject to modifications.

Variables on the drawing are dependent upon the motor.
The given dimensions are exemplary.

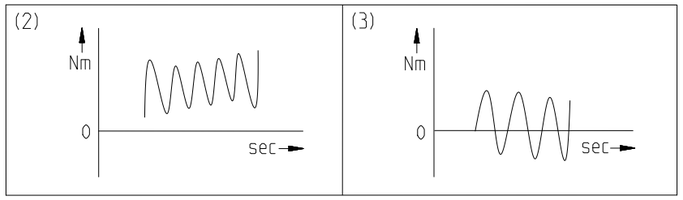


NEUGART	Scale: 7:10	DIN A3	ISO
	Revision status: E from: 04/2022		
	Changed revision status: D from: 03/2020		
General tolerance DIN ISO 2768-cL	PSN070-aii-SSSA3AD-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Helical teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	1-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/220)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	18
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	-	0,02 / 0,04 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20\ min}$	mm	22
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20.000h with Fa=0N	$F_{r\ 20.000h}$	N	3200
Axial force for output bearing based on gearbox axis after L10h=20.000h with Fr=0N	$F_{a\ 20.000h}$	N	4400
Radial force for output bearing based on shaft center after L10h=30.000h with Fa=0N	$F_{r\ 30.000h}$	N	3200
Axial force for output bearing based on gearbox axis after L10h=30.000h with Fr=0N	$F_{a\ 30.000h}$	N	3900
Maximum radial force based on shaft center and T2=0Nm	$F_{r\ Max}$	N	3200
Maximum axial force based on gearbox axis and T2=0Nm	$F_{a\ Max}$	N	4400

(1) Max. motor weight* in kg = $\dfrac{0{,}2 \times M_b}{\text{motor length in m}}$

* with symmetrically distributed motor weight
* with horizontal and stationary mounting



Ratio-dependent gearbox data	Character	Unit						
Ratio	aii	-	3	4	5	7	8	10
Nominal output torque No alternating torque (2)	T_{2N}	Nm	29	39	40	37	39	28
Nominal output torque Alternating torque permitted for 10.000.000 load changes (3)	$T_{2N\ 10Mio}$	Nm	29	37	37	37	37	28
Nominal output torque Alternating torque permitted for 100.000.000 load changes (3)	$T_{2N\ 100Mio}$	Nm	29	29	29	29	29	28
Max. output torque for 30.000 output shaft rotations (2)	T_{2max}	Nm	46	62	64	59	62	45
Emergency stop torque permitted 1000 times	T_{2Stop}	Nm	90	120	130	80	90	90
Average idle torque for n1=3.000 rpm and 20 °C gearbox temperature	T_0	Nm	0,65	0,45	0,35	0,25	0,25	0.2
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N\ 50\%}$	rpm	3000	3700	4400	4500	4500	4500
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N\ 100\%}$	rpm	2850	3400	4050	4500	4500	4500
Max. mechanical input speed Operating temperature may not be exceeded!	$n_{1\ Limit}$	rpm	14000	14000	14000	14000	14000	14000
Torsional backlash based on output shaft	j_t	arcmin	< 3	< 3	< 3	< 3	< 3	< 3
Torsional stiffness based on output shaft	c_g	Nm/arcmin	4,2	4,4	4,5	4,3	4,3	3,8
Efficiency at T2N, gearbox temperature 70 °C and n1=1.000rpm	η	%	97	97	97	97	96	95
Running noise at n1=3.000 rpm without load at a distance of 1m	Q_g	dB(A)	63	57	57	57	57	57
Gearbox weight	m_G	kg	2.2	2.2	2.2	2.2	2.2	2.2
Mass moment of inertia based on clamping system diameter input	J	kgcm²	0,294	0,216	0,187	0,162	0,157	0,15

Subject to modifications.

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PSN070-aii-SSSA3AD-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)

Revision status: E from: 04/2022