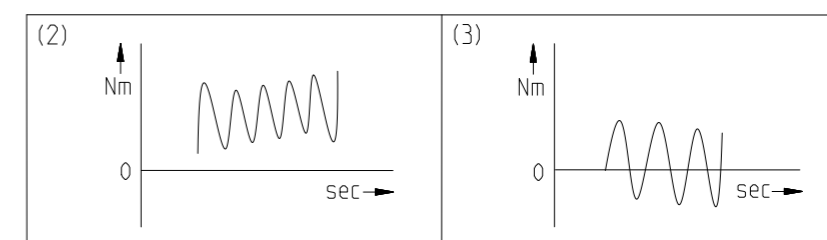
	Scale: 1:2	DIN A3	ISO
	Revision status: L from: 05/2022		
	Changed revision status: K from: 07/2020		
General tolerance DIN ISO 2768-cL	PLN115-bii-SSSA3AF-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	2-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/150)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	80
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	-	0,015 / 0,03 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20 min}$	mm	19
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20,000h with Fa=0N	$F_{r 20.000h}$	N	6000
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	$F_{a 20.000h}$	N	8000
Radial force for output bearing based on shaft center after L10h=30,000h with Fa=0N	$F_{r 30.000h}$	N	5400
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	$F_{a 30.000h}$	N	7000
Maximum radial force based on shaft end and T2=0Nm	$F_{r Max}$	N	6000
Maximum axial force based on gearbox axis and T2=0Nm	$F_{a Max}$	N	8000

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting



Ratio-dependent gearbox data	Character	Unit									
Ratio	bii	-	12	15	16	20	25	32	40	64	100
Nominal output torque No alternating torque (2)	T_{2N}	Nm	250	250	300	300	260	300	260	150	125
Nominal output torque Alternating torque permitted for 10,000,000 load changes (3)	$T_{2N 10Mio}$	Nm	239	239	239	239	239	239	239	150	125
Nominal output torque Alternating torque permitted for 100,000,000 load changes (3)	$T_{2N 100Mio}$	Nm	190	190	190	190	190	190	190	150	125
Max. output torque for 30,000 output shaft rotations	T_{2max}	Nm	400	400	480	480	416	480	416	240	200
Emergency stop torque permitted 1000 times	T_{2stop}	Nm	500	500	650	650	650	650	650	380	480
Average idle torque for $n_1=3,000$ rpm and 20 °C gearbox temperature	T_0	Nm	1,75	1,25	1,75	1,25	1,2	0,8	0,75	0,75	0,65
Average thermal input speed at 50% T_{2N} , S1, and T_{Amb} Operating temperature may not be exceeded!	$n_{1N 50\%}$	rpm	2450	3000	2550	3050	3400	3500	3500	3500	3500
Average thermal input speed at 100% T_{2N} , S1, and T_{Amb} Operating temperature may not be exceeded!	$n_{1N 100\%}$	rpm	1950	2350	2050	2450	2850	3350	3500	3500	3500
Max. mechanical input speed Operating temperature may not be exceeded!	$n_{1 Limit}$	rpm	8500	8500	8500	8500	8500	8500	8500	8500	8500
Torsional backlash based on output shaft	j_t	arcmin	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5
Torsional stiffness based on output shaft	c_g	Nm/arcmin	22,5	22,5	24,5	24,5	26	24,5	26	22,5	22,5
Efficiency at T_{2N} , gearbox temperature 70 °C and $n_1=1,000$ rpm	η	%	95	95	95	95	94	94	93	88	82
Running noise at $n_1=3,000$ rpm without load at a distance of 1m	Q_g	dB(A)	67	67	67	65	65	65	65	65	65
Gearbox weight	m_G	kg	8,9	8,9	8,9	8,9	8,9	9	8,9	9	8,2
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	2,373	2,172	2,33	2,155	2,134	1,967	1,963	1,959	1,933

Subject to modifications.



PLN115-bii-SSSA3AF-Z(D20)
/(L20)/(D21)/(D22)/B5/(G3)

Sheet 2/2

Revision status: L from: 05/2022