

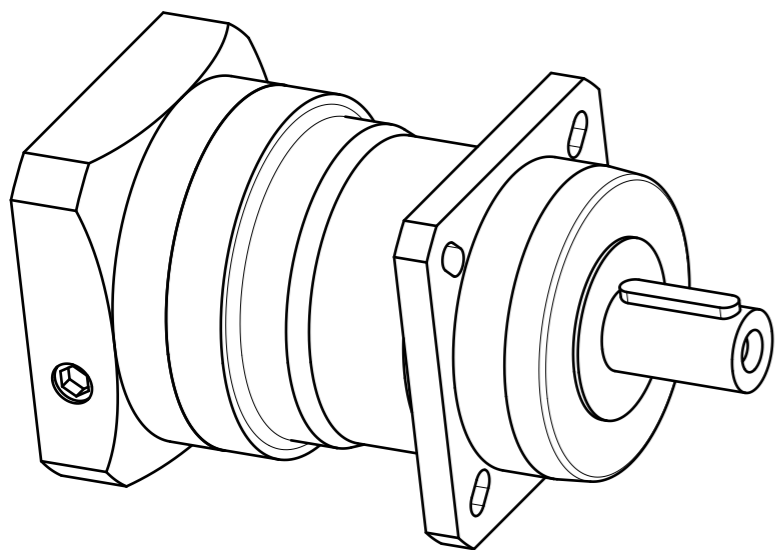
Materials / Surfaces:


Input flange: Aluminum / untreated
Housing: Steel / heat-treated and post-oxidized (black)
Output flange: Steel / untreated

Hints:

Please pay attention to the operating and mounting instructions.
Subject to modifications.

Variables on the drawing are dependent upon the motor.
The given dimensions are exemplary.

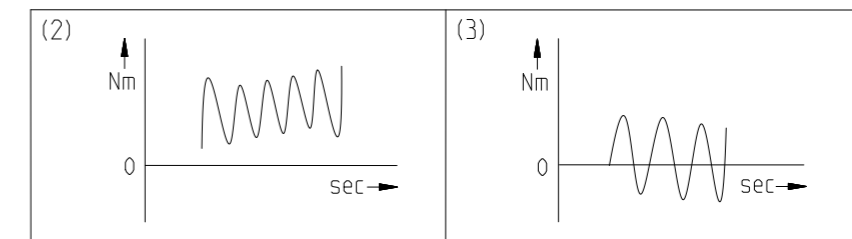


	Scale: 9:10	DIN A3	ISO
	Revision status: L from: 05/2022		
	Changed revision status: K from: 07/2020		
General tolerance DIN ISO 2768-cL	PLN070-aii-SSSA3AD-Z(D20) /(L20)/(D21)/(D22)/B5/(G3)		
Neugart GmbH Keltenstr. 16 D-77971 Kippenheim			Sheet 1/2

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	1-stage
Output shaft bearing	-	-	Tapered roller bearing
Service life (L10h)	t_L	h	20.000
Max. operating temperature	T_{min} / T_{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (lifetime lubrication)	-	-	Standard lubrication (Castrol Optigear Synthetic 800/150)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M_b	Nm	18
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	-	0,015 / 0,03 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	$L_{20 min}$	mm	15
Reference operating mode	-	-	S1
Reference operating factor	K_A	-	1
Reference speed	n_2	rpm	100
Reference ambient temperature	T_{Amb}	°C	20
Radial force for output bearing based on shaft center after L10h=20,000h with Fa=0N	$F_{r 20.000h}$	N	3200
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	$F_{a 20.000h}$	N	4400
Radial force for output bearing based on shaft center after L10h=30,000h with Fa=0N	$F_{r 30.000h}$	N	3200
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	$F_{a 30.000h}$	N	3900
Maximum radial force based on shaft end and T2=0Nm	$F_{r Max}$	N	3200
Maximum axial force based on gearbox axis and T2=0Nm	$F_{a Max}$	N	4400

$$(1) \text{ Max. motor weight* in kg} = \frac{0,2 \times M_b}{\text{motor length in m}}$$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting



Ratio-dependent gearbox data	Character	Unit							
Ratio	aii	-	3	4	5	7	8	10	
Nominal output torque No alternating torque (2)	T_{2N}	Nm	45	60	65	45	40	27	
Nominal output torque Alternating torque permitted for 10,000,000 load changes (3)	$T_{2N 10Mio}$	Nm	37	37	37	37	37	27	
Nominal output torque Alternating torque permitted for 100,000,000 load changes (3)	$T_{2N 100Mio}$	Nm	29	29	29	29	29	27	
Max. output torque for 30,000 output shaft rotations	T_{2max}	Nm	72	96	104	72	64	43	
Emergency stop torque permitted 1000 times	T_{2stop}	Nm	90	120	130	80	90	90	
Average idle torque for $n_1=3,000$ rpm and 20 °C gearbox temperature	T_0	Nm	0,7	0,5	0,4	0,35	0,3	0,25	
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 50\%}$	rpm	2050	2300	2650	3450	3800	4400	
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	$n_{1N 100\%}$	rpm	1700	1900	2100	2950	3300	4000	
Max. mechanical input speed Operating temperature may not be exceeded!	$n_{1 Limit}$	rpm	14000	14000	14000	14000	14000	14000	
Torsional backlash based on output shaft	j_t	arcmin	< 3	< 3	< 3	< 3	< 3	< 3	
Torsional stiffness based on output shaft	c_g	Nm/arcmin	4,3	4,4	4,5	4	4	3,6	
Efficiency at T2N, gearbox temperature 70 °C and $n_1=1,000$ rpm	η	%	96	97	97	95	95	92	
Running noise at $n_1=3,000$ rpm without load at a distance of 1m	Q_g	dB(A)	68	62	60	60	60	60	
Gearbox weight	m_G	kg	2	1,95	1,95	1,95	2	2	
Mass moment of inertia based on clamping system diameter input	J	kgcm ²	0,365	0,282	0,252	0,228	0,223	0,216	

Subject to modifications.



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/(L20)/(D21)/(D22)/B5/(G3)

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